# Q4X Stainless Steel Laser Sensor

Instruction Manual

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## Contents

1 Product Description	3
1.1 Models	
1.2 Overview	
1.3 Features	
1.3.1 Display and Indicators	
1.3.2 Buttons	
1.4 Laser Description and Safety Information	
2 Installation	
2.1 Install the Safety Label	
2.2 Sensor Orientation	
2.3 Mount the Sensor	
2.4 Wiring Diagram—Threaded Barrel Models	
2.5 Wiring Diagram—Flush Mount Models	/
2.6 Cleaning and Maintenance	
3 Sensor Programming	
3.1 Light Operate/Dark Operate 3.2 Setup Mode	8
3.2 Setup Mode 3.2.1 TEACH Mode	
3.2.2 Adaptive Tracking 3.2.3 Response Speed	10۱۵ ۱۸
3.2.4 Gain and Sensitivity	
3.2.5 Output Timing Delays	
3.2.6 Delay Timers	
3.2.7 Zero Reference Location	
3.2.8 Shift the Zero Reference Location after a TEACH	
3.2.9 Input Wire Function	
3.2.10 Display View	13
3.2.11 Exit Setup Mode	
3.2.12 Reset to Factory Defaults	
3.3 Manual Adjustments	
3.4 Remote Input	
3.4.1 Select the TEACH Mode Using the Remote Input	
3.5 Locking and Unlocking the Sensor Buttons	10 15
3.6 TEACH Procedures	16
3.6.1 Two-Point Static Background Suppression	
3.6.2 Dynamic Background Suppression	
3.6.3 One-Point Window (Foreground Suppression)	
3.6.4 One-Point Background Suppression 3.6.5 Dual (Intensity + Distance)	
3.6.5 Dual (Intensity + Distance)	
3.7 Sync Master/Slave	24
4 Specifications	25
4.1 Dimensions	
4.2 Performance Curves—Threaded Barrel Models	
4.3 Performance Curves—Flush Mount Models	
5 Additional Information	
5.1 Dual (Intensity + Distance) Mode	
5.2 Dual Mode Reference Surface Considerations	
5.3 Dual Mode Considerations for Clear and Transparent Object Detection	
6 Troubleshooting	
5	
7 Accessories 7.1 Cordsets—Threaded Barrel Models	
7.1 Cordsets—Threaded Barrel Models 7.2 Cordsets—Flush Mount Models	
7.3 Brackets	
7.4 Aperture Kits—Threaded Barrel Models	
7.5 Reference Targets	
8 Contact Us	
9 Banner Engineering Corp. Limited Warranty	

## 1 Product Description

Class 1 laser CMOS sensor with a discrete (PNP or NPN) output. Patent pending.

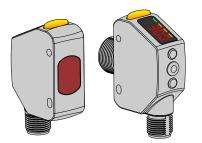


Figure 1. Flush Mount (Left) and Threaded Barrel (Right) Models

- The ultimate problem solver: reduce sensor inventory with a reliable, durable sensor that solves the most challenging applications
- Solves difficult distance-based applications regardless of target surface reflectivity, including black foam on black plastic, black rubber in front of metal, transparent objects, multicolor packaging, and targets of all colors
- Reliable sensing range of 25 mm to 300 mm (0.98 in to 11.81 in) for threaded barrel models or 35 mm to 110 mm (1.38 in to 4.33 in) for flush mount models, with best in class excess gain
- Angled four-digit display with submillimeter resolution is easily viewed from multiple vantage points
- Display provides clear user feedback for easy setup, and bright output indicator provides high visibility of sensor operation
- Intuitive setup using three tactile buttons conveniently located below the display
- Durable and robust construction resists mechanical impact, over tightening, and extreme vibration
- FDA grade stainless steel and plastics, ECOLAB<sup>®</sup> certified chemically-resistant materials, and laser marked sensor information withstands aggressive cleaning procedures
- Superior resistance to ambient light interference prevents nuisance output trips under changing lighting conditions
- Temperature-compensated design ensures reliable detection during changing temperature conditions

For illustration purposes, the threaded barrel model Q4X images are used throughout this document.



WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition.

### 1.1 Models

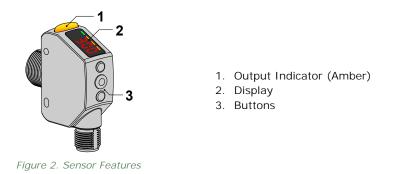
Model		Sensing Range	Output	Connection <sup>1</sup>	
	Q4XTBLAF300-Q8	25 mm to 300 mm (0.98 in to 11.81 in)	Bipolar: 1 NPN; 1 PNP	Integral 5-pin M12/Euro-style	
	Q4XTBLAF100-Q8	25 mm to 100 mm (0.98 in to 3.94 in)	Bipolar: 1 NPN; 1 PNP	male quick disconnect (QD)	
	Q4XFNLAF310-Q8	35 mm to 310 mm (1.38 in to 12.20 in)	NPN	Integral 4-pin M12/Euro-style male quick disconnect (QD)	
	Q4XFPLAF310-Q8	35 mm to 310 mm (1.38 in to 12.20 in)	PNP		
	Q4XFNLAF110-Q8	35 mm to 110 mm (1.38 in to 4.33 in)	NPN	Integral 4-pin M12/Euro-style	
	Q4XFPLAF110-Q8	35 mm to 110 mm (1.38 in to 4.33 in)	PNP	male quick disconnect (QD)	

<sup>1</sup> QD models require a mating cordset.

## 1.2 Overview

The Q4X Sensor is a Class 1 laser CMOS sensor with a bipolar output. The normal sensor state is Run mode. From Run mode, the switch point value and LO/DO selection can be changed and the selected TEACH method can be performed. The secondary sensor state is Setup mode. From Setup mode, the TEACH mode can be selected, all standard operating parameters can be adjusted, and a factory reset can be done.

## 1.3 Features



### 1.3.1 Display and Indicators

The display is a 4-digit, 7-segment LED. The main screen is the Run mode screen.

For 2-pt, BGS, FGS, and DYN TEACH modes, the display shows the current distance to the target in millimeters. For dual

TEACH mode, the display shows the percentage matched to the taught reference surface. A display value of indicates the sensor has not been taught.



Figure 3. Display in Run Mode

Output Indicator

- On—Outputs conducting (closed)
- Off—Outputs not conducting (open)

Active TEACH Indicators (DYN, FGS, and BGS)

- DYN, FGS, and BGS all off—Two-point TEACH mode selected (default)
- DYN on—Dynamic TEACH mode selected
- FGS on—Foreground suppression TEACH mode selected
- BGS on—Background suppression TEACH mode selected
- DYN, FGS, and BGS all on—Dual TEACH mode selected

1. Stability Indicator (STB-Green)

- 2. Active TEACH Indicators
  - DYN—Dynamic (Amber)
  - FGS—Foreground Suppression (Amber)
  - BGS—Background Suppression (Amber)

Stability Indicator (STB)

- On—Stable signal within the specified sensing range
- Flashing—Marginal signal, the target is outside the limits of the specified sensing range, or a multiple peak condition exists
- Off—No target detected within the specified sensing range

### 1.3.2 Buttons

Use the sensor buttons (SELECT)(TEACH), (+)(DISP), and (-)(MODE) to program the sensor.



#### (SELECT) (TEACH)

- Press to select menu items in Setup mode
- Press and hold for longer than 2 seconds to start the currently selected TEACH mode (the default is two-point TEACH)

#### (-)(MODE)

- · Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to decrease numeric values
- Press and hold for longer than 2 seconds to enter Setup mode

#### (+)(DISP)

- Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to increase numeric values
- Press and hold for longer than 2 seconds to switch between light operate (LO) and dark operate (DO)



NOTE: When navigating the menu, the menu items loop.

## 1.4 Laser Description and Safety Information



CAUTION: Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure. Do not attempt to disassemble this sensor for repair. A defective unit must be returned to the manufacturer.

#### Class 1 Lasers

Class 1 lasers are lasers that are safe under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.



Laser wavelength: 655 nm

Output: < 0.20 mW

Pulse Duration: 7 µs to 2 ms

## 2 Installation

## 2.1 Install the Safety Label

The safety label must be installed on Q4X sensors that are used in the United States.



NOTE: Position the label on the cable in a location that has minimal chemical exposure.

- 1. Remove the protective cover from the adhesive on the label.
- 2. Wrap the label around the Q4X cable, as shown.
- 3. Press the two halves of the label together.

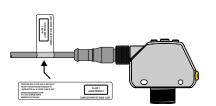


Figure 4. Safety Label Installation

### 2.2 Sensor Orientation

Optimize detection reliability and minimum object separation performance with correct sensor-to-target orientation. To ensure reliable detection, orient the sensor as shown in relation to the target to be detected.

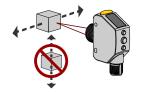


Figure 5. Optimal Orientation of Target to Sensor

See the following figures for examples of correct and incorrect sensor-to-target orientation as certain placements may pose problems for sensing some targets. The Q4X can be used in the less preferred orientation and provide reliable detection performance; refer to the Performance Curves for the minimum object separation distance required for each case.

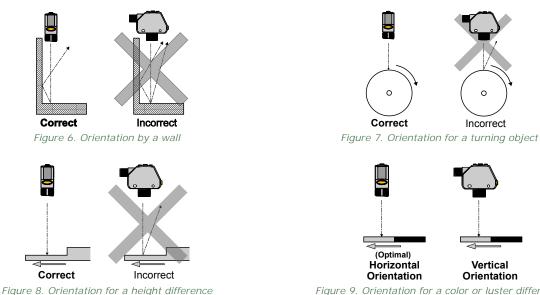


Figure 9. Orientation for a color or luster difference

### 2.3 Mount the Sensor

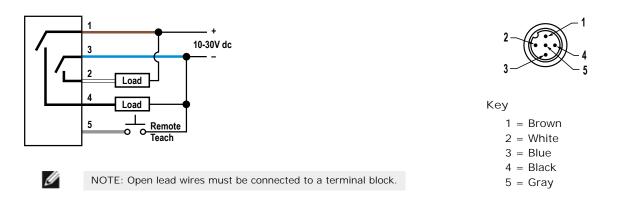
- 1. If a bracket is needed, mount the sensor onto the bracket.
- 2. Mount the sensor (or the sensor and the bracket) to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.

3. Check the sensor alignment.

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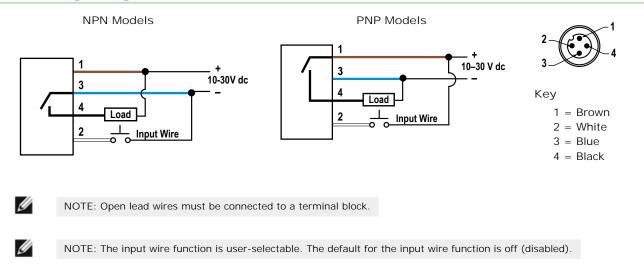
4. Tighten the mounting screws to secure the sensor (or the sensor and the bracket) in the aligned position.

### 2.4 Wiring Diagram—Threaded Barrel Models



NOTE: The input wire function is user-selectable. The default for the input wire function is off (disabled).

### 2.5 Wiring Diagram—Flush Mount Models



### 2.6 Cleaning and Maintenance

Handle the sensor with care during installation and operation. Sensor windows soiled by fingerprints, dust, water, oil, etc. may create stray light that may degrade the peak performance of the sensor. Blow the window clear using filtered, compressed air, then clean as necessary using water and a lint-free cloth.

## 3 Sensor Programming

Program the sensor using the buttons on the sensor or the remote input (limited programming options).

In addition to programming the sensor, use the remote input to disable the buttons for security, preventing unauthorized or accidental programming changes. See *Locking and Unlocking the Sensor Buttons* on page 15 for more information.

## 3.1 Light Operate/Dark Operate

The default output configuration is light operate. To switch between light operate and dark operate, use the following instructions:

- 1. Press and hold LO/DO for longer than 2 seconds. The current selection displays.
- 2. Press LO/DO again. The new selection flashes slowly.
- 3. Press SELECT to change the output configuration and return to Run mode.



NOTE: If neither SELECT nor LO/DO are pressed after step 2, the new selection flashes slowly for a few seconds, then flashes quickly and the sensor automatically changes the output configuration and returns to Run mode.

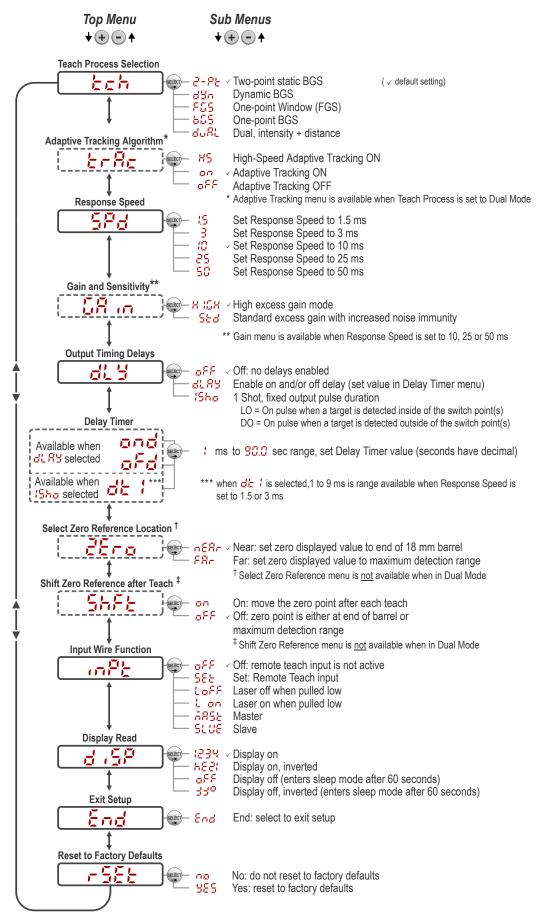
### 3.2 Setup Mode

Access Setup mode and the sensor menu from Run mode by pressing and holding MODE for longer than 2 seconds. Use

 $\bullet$  and  $\bullet$  to navigate through the menu. Press SELECT to select a menu option and access the submenus. Use  $\bullet$  and

• to navigate through the submenus. Press SELECT to select a submenu option and return to the top menu, or press and hold SELECT for longer than 2 seconds to select a submenu option and return immediately to Run mode.

To exit Setup mode and return to Run mode, navigate to  $\frac{\xi \sigma d}{\sigma}$  and press SELECT.



## 3.2.1 TEACH Mode

Use this menu to select the TEACH mode. The default is two-point TEACH.

- *C-PL*—Two-point static background suppression
- Dynamic background suppression
- F25 —One-point window (foreground suppression)
- **bC5** —One-point background suppression
- Dual (intensity + distance) window

After the TEACH mode is selected, from Run mode, press and hold TEACH for longer than 2 seconds to start the TEACH mode and program the sensor. See *TEACH Procedures* on page 16 for additional information and remote input TEACH instructions.

## 3.2.2 Adaptive Tracking

Use these menus to set the adaptive tracking algorithm. This menu is available only if dual (intensity + distance) mode is selected.

- High-Speed Adaptive Tracking On
- — Adaptive Tracking On (default)
- Adaptive Tracking Off

## 3.2.3 Response Speed

Use this menu to select the response speed. The default is 10 milliseconds.

- <sup>6</sup>—1.5 milliseconds
- 3 milliseconds
- <sup>[]</sup> —10 milliseconds
- 25 —25 milliseconds
- 50 milliseconds

#### Table 1: Tradeoffs

Response Speed	Response Speed in Sync Mode	Repeatability	Ambient Light Rejection	Excess Gain
1.5 ms	3 ms	500 µs	Disabled	
3 ms	6 ms	500 µs	Enabled	
10 ms	20 ms	2 ms	Enabled	See Table 11 on page
25 ms	50 ms	5 ms	Enabled	
50 ms	100 ms	10 ms	Enabled	

## 3.2.4 Gain and Sensitivity

Use this menu to set the excess gain mode. This menu is only available when a 10, 25, or 50 millisecond response speed is selected. It is not available for 1.5 or 3 millisecond response speeds.

- H I High excess gain mode
  - 560 Standard excess gain mode with increased noise immunity

## 3.2.5 Output Timing Delays

Use this menu to select the output timing delay to be set. On and off delay timers can be used together. The default is no delay.

- ●<sup>F,F</sup> —No delay
- Delay-enables the selection of on and off delay timers
- -One-shot—enables a one-shot, fixed output pulse duration

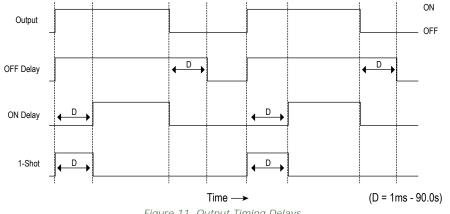


Figure 11. Output Timing Delays

When one of the timing delay options is chosen, the sensor returns to the Setup menu and additional options become available to set the parameter(s):

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- On delay
- o<sup>F</sup>d −Off delay

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- delay timer
  - NOTE: For the one-shot delay timer:
    - LO = On pulse when a target is detected inside of the switch point(s)
    - DO = On pulse when a target is detected outside of the switch point(s)

## 3.2.6 Delay Timers and and del

Use these menus to set the delay timers. These menus are available only if an output timing delay is selected.

For  $\mathbf{Q} = \mathbf{Q} \mathbf{Q}$  and  $\mathbf{Q} = \mathbf{Q} \mathbf{Q}$ , the default is 0.

For 💏 🦕 , the default is 10 milliseconds for 10, 25, and 50 millisecond response speeds and 1 millisecond for 1.5 and 3 milliseconds response speeds.

Use 😁 and 😑 to scroll through the values. Values greater than 10 increase or decrease by increments of 10. Millisecond values do not include the decimal point; seconds values include the decimal point.

- 1 to 9 ms (when discussed, the 1 to 9 ms range is available for 1.5 and 3 ms response times)
- 10 to 90 ms
- 100 to 900 ms
- 1.0 to 90.0 s

## 3.2.7 Zero Reference Location

Use this menu to select the zero reference location. The default is  $n \in \mathbb{R}^{n}$ , 0 = the end of the sensor barrel. This menu is not available in dual (intensity + distance) mode.

- $\frac{1}{100}$   $\frac{1}{100}$  -0 = the end of the sensor barrel; the measurement increases further from the sensor
- FR- -0 = maximum range; the measurement increases closer to the sensor

## 3.2.8 Shift the Zero Reference Location after a TEACH

Use this menu to select whether the sensor shifts the zero reference location based on the last TEACH process. The default

- is  $\sigma^{FF}$ , 0 = the end of barrel or the maximum range. This menu is not available in dual (intensity + distance) mode.

  - $\Box^{FF} = -0$  = the end of barrel or the maximum range, depending on the  $\Xi^{FF} =$  setting

This figure illustrates three examples of how changes to the zero and shift settings affect what distance readout is shown on the display when in 2-pt TEACH mode. Changes to the zero setting affect the direction in which the distance increases.

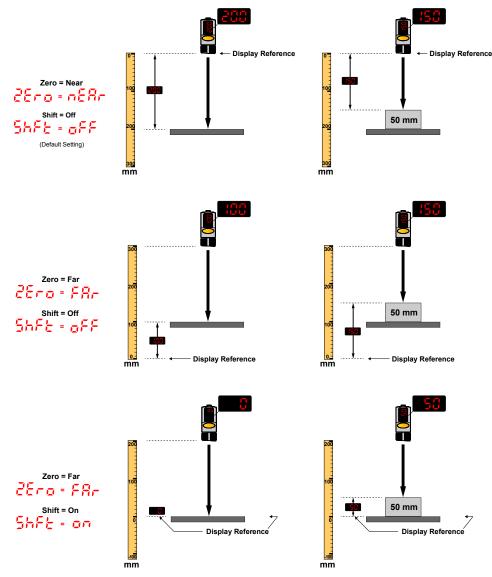


Figure 12. Example Zero and Shift settings

## 3.2.9 Input Wire Function

Use this menu to select the input wire function. The default is off, ignore all remote input pulses.

- **SEE** —Remote TEACH input
- Loff —Laser off when pulled low
- Laser on when pulled low

- Master sync line output for two-sensor cross-talk avoidance
- Slave sync line input for two-sensor cross-talk avoidance

To configure sensors for master-slave operation, see Sync Master/Slave on page 24.

## 3.2.10 Display View d 🛱

Use this menu to select the display view. The default is right-reading.

- **Right-reading**
- **HER**—Inverted
- **GFF** —Right-reading and the display enters sleep mode after 60 seconds
- $\frac{1}{2}$  —Inverted and the display enters sleep mode after 60 seconds

When the sensor is in sleep mode, the display wakes with the first button press.

## 3.2.11 Exit Setup Mode End

Navigate to End and press SELECT to exit Setup mode and return to Run mode.

## 3.2.12 Reset to Factory Defaults

Use this menu to restore the sensor to the factory default settings. See Factory Default Settings on page 13.

Select no to return to the sensor menu without restoring the defaults. Select  $\frac{45}{5}$  to apply the factory defaults and return to Run mode.

#### Factory Default Settings

Setting	Factory Default
Delay Timers ( 🖧 💆 )	₽ <sup>F,F</sup> —No delay
Display View ( 🖞 کې )	년글거 —Right-reading, no sleep mode
Gain and Sensitivity ( 💭 🦛 )	H IGH —High excess gain mode
Input Wire Function ( <sup>(1)2</sup> 5)	$o^{FF}$ —Ignore all remote input pulses If the sensor was reset using the remote input, the sensor remains in $5EE$ mode to allow use of the remote input.
LO/DO	LO—Light Operate
Response Speed ( 5.9 d )	<sup>10</sup> −10 ms
Shift the Zero Reference Location after a TEACH ( 5,5,5,5)	$\Box^{FF}$ —0 = the end of barrel
TEACH Mode ( = = )	<del>کام ک</del> ے
Zero Reference Location ( 25, 0)	

### 3.3 Manual Adjustments

Manually adjust the sensor switch point using the  $\textcircled{\bullet}$  and  $\textcircled{\bullet}$  buttons.

1. From Run mode, press either  $\bullet$  or  $\bullet$  one time. The current switch point value flashes slowly.

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2. Press  $\textcircled{\bullet}$  to move the switch point up or  $\textcircled{\bullet}$  to move the switch point down. After 1 second of inactivity, the new switch point value flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.

NOTE: When FGS mode is selected (FGS indicator is on), manual adjustment moves both sides of the symmetrical threshold window simultaneously, expanding and collapsing the window size. Manual adjustment does not move the center point of the window.

NOTE: When dual mode is selected (DYN, FGS, and BGS indicators are on), after the TEACH process is completed, use the manual adjustment to adjust the sensitivity of the thresholds around the taught reference point. The taught reference point is a combination of the measured distance and returned signal intensity from the reference

target. Manual adjustment does not move the taught reference point, but pressing 🙂 increases the sensitivity,

and pressing educreases the sensitivity. When re-positioning the sensor or changing the reference target, re-teach the sensor.

### 3.4 Remote Input

Use the remote input to program the sensor remotely. The remote input provides limited programming options and is Active Low. For Active Low, connect the gray input wire to ground (0 V dc), with a remote switch connected between the wire and ground. Pulse the remote input according to the diagram and the instructions provided in this manual.

The length of the individual programming pulses is equal to the value T: 0.04 seconds  $\leq T \leq 0.8$  seconds.

Exit remote programming modes by setting the remote input Low for longer than 2 seconds.

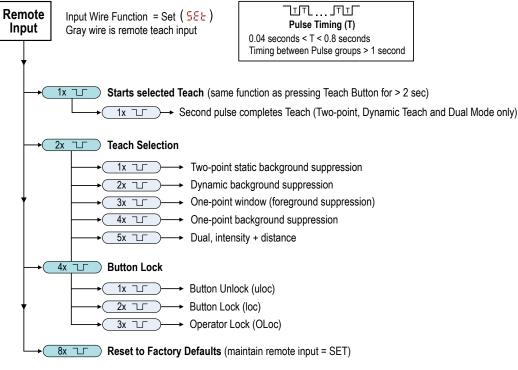


Figure 13. Remote Input Map

### 3.4.1 Select the TEACH Mode Using the Remote Input

1. Access the TEACH selection.

Action	Result
Double-pulse the remote input.	<mark>ትድት</mark> displays.

2. Select the desired TEACH mode.

Action		Result
Pulses	TEACH Mode	
1	Two-point static background suppression	
2	Dynamic background suppression	
3	One-point window (foreground suppression)	The selected TEACH method displays for a few seconds and the sensor returns to Run mode.
4	One-point background suppression	
5	Dual (intensity + distance)	

### 3.4.2 Reset to Factory Defaults Using the Remote Input

Eight-pulse the remote input to apply the factory defaults and return to Run mode.





NOTE: The input wire function remains at remote teach input (55).

### 3.5 Locking and Unlocking the Sensor Buttons

Use the lock and unlock feature to prevent unauthorized or accidental programming changes. Three settings are available:

- where the sensor is unlocked and all settings can be modified (default).
- $L_{\text{DC}}$  The sensor is locked and no changes can be made.
- CLOC —The switch point value can be changed by teaching or manual adjustment, but no sensor settings can be changed through the menu.

When in  $L^{OC}$  mode,  $L^{OC}$  displays when the (SELECT) (TEACH) button is pressed. The switch point displays when (+) (DISP) or (-) (MODE) are pressed, but  $L^{OC}$  displays if the buttons are pressed and held.

When in ULDE mode, LOE displays when (+)(DISP) or (-)(MODE) are pressed and held. To access the manual adjust options, briefly press and release (+)(DISP) or (-)(MODE). To enter TEACH mode, press the (SELECT)(TEACH) button and hold for longer than 2 seconds.

Button Instructions

To enter  $\mathbf{L} \mathbf{p} \mathbf{c}$  mode, hold  $\mathbf{e}$  and press  $\mathbf{e}$  four times. To enter  $\mathbf{p} \mathbf{c} \mathbf{p} \mathbf{c}$  mode, hold  $\mathbf{e}$  and press  $\mathbf{e}$  seven times. Holding  $\mathbf{e}$  and pressing  $\mathbf{e}$  four times unlocks the sensor from either lock mode and the sensor displays  $\mathbf{p} \mathbf{c} \mathbf{p} \mathbf{c}$ .

Remote Input Instructions

1. Access the remote input.

Action	Result
Four-pulse the remote input.	The sensor is ready to have the button state defined and bc displays.

2. Lock or unlock the sensor buttons.

Action	Result
Single-pulse the remote input to unlock the sensor.	Run mode.
Double-pulse the remote input to lock the sensor.	displays and the sensor returns to Run mode.
Triple-pulse the remote input to apply the operator lock to the sensor	CLOC displays and the sensor returns to Run mode

## 3.6 TEACH Procedures

Use the following procedures to teach the sensor.

To cancel a TEACH procedure, press TEACH for longer than 2 seconds, or hold the remote input Low for longer than 2 seconds.

## 3.6.1 Two-Point Static Background Suppression

Two-point TEACH sets a single switch point. The sensor sets the switch point between two taught target distances, relative to the shifted origin location.

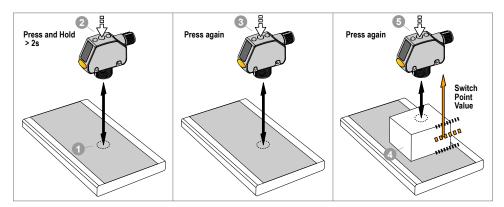


Figure 14. Two-Point Static Background Suppression (Light Operate shown)

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NOTE: The sensor must be set to  $\frac{1}{2} = \frac{2}{2} - \frac{2}{2} \frac{1}{2}$  to use the following instructions.

NOTE: To program the sensor using remote input, remote input must be enabled (  $\frac{1}{1000} = \frac{55}{1000}$  ).

1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within	The target's measurement value
Remote Input	the sensor's range.	displays.

2. Start the TEACH mode.

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Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	<b>56</b> and <b>15</b> flash alternately on the display. The DYN, FGS, and BGS indicators flash.
Remote Input	No action required.	N/A

### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	The sensor is taught the first target.
Remote I nput	Single-pulse the remote input.	<b>5EE</b> , <b>2nd</b> , and the current distance measurement flash alternately on the display. The DYN, FGS, and BGS indicators flash.

#### 4. Present the target.

Method	Action	Result
Push Button		585 , 2nd , and the distance
Remote Input	Present the second target. The sensor-to-target distance must be within the sensor's range.	measurement flash alternately on the display. The DYN, FGS, and BGS indicators flash.

#### 5. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The new switch point flashes rapidly and the sensor returns to Run mode.

## Table 2: Expected TEACH Behavior for Two-Point Static Background SuppressionSee Figure 20 on page 28 for the minimum object separation.

Condition	TEACH Result		Display
Two valid distances that are greater than or equal to the horizontal minimum object separation	Sets a switch point between the two taught distances.		The switch point distance flashes on the display.
Two valid distances that are less than the horizontal minimum object separation	Sets a switch point in front of the furthest taught distance by the horizontal minimum object separation.		<b>505</b> and the switch point distance flash alternately on the display.
One valid distance with one invalid TEACH point	Sets a switch point between the one taught distance and the maximum range.		obut and the switch point distance flash alternately on the display.
Two invalid TEACH points	Sets a switch point at the following location: $F_{\omega}$		Full and the switch point
	Model	Switch Point	distance flash alternately on the display.
	100 mm threaded barrel models	99	
	300 mm threaded barrel models	290	
	110 mm flush mount models	109	
	310 mm flush mount models	300	

## 3.6.2 Dynamic Background Suppression

Dynamic TEACH sets a single switch point during machine run conditions. Dynamic TEACH is recommended for applications where a machine or process may not be stopped for teaching. The sensor takes multiple samples and the switch point is set between the minimum and the maximum sampled distances.

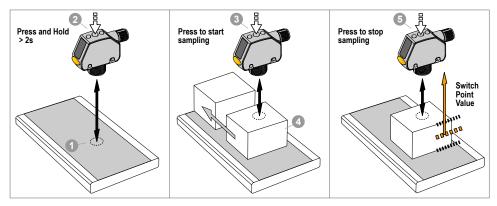


Figure 15. Dynamic Background Suppression



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NOTE: The sensor must be set to c c = c c to use the following instructions. The DYN indicator is amber to indicate Dynamic TEACH mode.

NOTE: To program the sensor using remote input, remote input must be enabled (  $\frac{1000}{1000} = \frac{560}{1000}$ ).

#### 1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within	The target's measurement value
Remote Input	the sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	or the display. The DYN indicator flashes.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	The sensor begins sampling target
Remote Input		distance information and $\frac{d^{2}}{5}$ and $\frac{5}{5}$ and $\frac{5}{5}$ flash alternately on the display. The DYN indicator flashes.

#### 4. Present the targets.

Method	Action	Result
Push Button Remote I nput	Present additional targets. The sensor-to-target distance must be within the sensor's range.	The sensor continues to sample target distance information and $d_{D}^{\dagger}$ and $f_{D}^{\dagger}$ flash alternately on the display. The DYN indicator flashes.

#### 5. Teach the sensor.

Method	Action		Result
Push Button	Press TEACH to stop teaching the sensor.		
Remote Input	Single-pulse the remote input.	Ţ	The new switch point flashes rapidly and the sensor returns to Run mode.

*Table 3: Expected TEACH Behavior for Dynamic Background Suppression* See *Figure 20* on page 28 for the minimum object separation.

Condition	TEACH Result		Display
Two valid distances that are greater than or equal to the horizontal minimum object separation	Sets a switch point between the two taught distances.		The switch point distance flashes on the display.
Two valid distances that are less than the horizontal minimum object separation	Sets a switch point in front of the furthest taught distance by the horizontal minimum object separation.		<b>b65</b> and the switch point distance flash alternately on the display.
One valid distance with one invalid TEACH point	Sets a switch point between the one taught distance and the maximum range.		obut and the switch point distance flash alternately on the display.
Two invalid TEACH points	Sets a switch point at the following location:		and the switch point
	Model	Switch Point	distance flash alternately on the display.
	100 mm threaded barrel models	75	
	300 mm threaded barrel models	200	
	110 mm flush mount models	85	
	310 mm flush mount models	210	

## 3.6.3 One-Point Window (Foreground Suppression)

One-point window sets a window (two switch points) centered around the taught target distance. Loss of signal is treated as a detection in One-Point Window mode. The size of the taught window is the vertical minimum object separation. See *Figure 20* on page 28.

Manually adjust the window size from Run mode using  $\textcircled{\bullet}$  and  $\textcircled{\bullet}$ .

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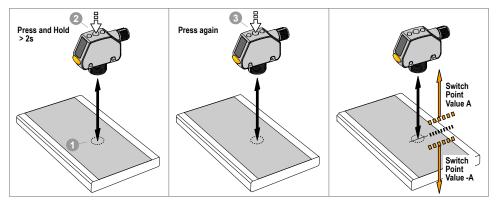


Figure 16. One-Point Window (Foreground Suppression)

NOTE: The sensor must be set to  $\frac{1}{2}$  =  $\frac{1}{2}$  to use the following instructions. The FGS indicator is amber to indicate One-Point Window (Foreground Suppression) mode.



NOTE: To program the sensor using remote input, remote input must be enabled (  $\frac{1000}{100} = 550$  ).

### 1. Present the target.

Method	Action	Result
Push Button	Present the target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

#### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	Light Operate 581: and 00 flash alternately on the display. The FGS indicator flashes. Dark Operate 561: and 066 flash alternately on the display. The FGS indicator flashes.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The ± window size flashes rapidly and the sensor returns to Run mode.

Table 4: Expected TEACH Behavior for One-Point Window (Foreground Suppression)See Figure 20 on page 28 for the minimum object separation.

Condition	TEACH Result	Display
One valid distance	Sets a window (two switch points) centered around the taught distance. The $\pm$ window size is the vertical minimum object separation. The two switch points always stay within the specified sensing range.	The $\pm$ window size flashes on the display.

Condition	TEACH Result		Display
One invalid TEACH Point	Sets a window (two switch po around the following location		point distance flash alternately on
	Model	Window Center Point	the display.
	100 mm threaded barrel models	80	
	300 mm threaded barrel models	250	
	110 mm flush mount models	90	
	310 mm flush mount models	260	
	The window size is:		
	Model	Window Size	
	100 mm threaded barrel models	±12.5 mm	
	300 mm threaded barrel models	± 25 mm	
	110 mm flush mount models	±12.5 mm	
	310 mm flush mount models	± 25 mm	
		~	

## 3.6.4 One-Point Background Suppression

One-point background suppression sets a single switch point in front of the taught target distance. Objects beyond the taught switch point are ignored. The switch point is set in front of the taught target distance by the vertical minimum object separation. See *Figure 20* on page 28.

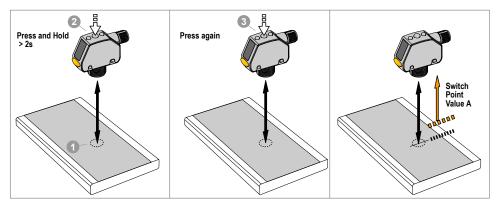


Figure 17. One-Point Background Suppression



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NOTE: The sensor must be set to  $\frac{1}{2}$   $\frac{1}{2}$   $\frac{1}{2}$  to use the following instructions. The BGS indicator is amber to indicate Background Suppression mode.

NOTE: To program the sensor using remote input, remote input must be enabled (  $10^{10}$  = 562 ).

#### 1. Present the target.

Method	Action	Result
Push Button	Present the target. The sensor-to-target distance must be within the	The target's measurement value
Remote Input	sensor's range.	displays.

2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold TEACH for longer than 2 seconds.	Light Operate SEE and OFF flash alternately on the display. The BGS indicator flashes. Dark Operate SEE and On flash alternately on the display. The BGS indicator flashes.
Remote Input	No action required.	N/A

3. Teach the sensor.

Method	Action	Result
Push Button	Press TEACH to teach the target.	
Remote Input	Single-pulse the remote input.	The new switch point flashes rapidly and the sensor returns to Run mode.

Table 5: Expected TEACH Behavior for One-Point Background Suppression See Figure 20 on page 28 for the minimum object separation.

TEACH Result	TEACH Result		
	Sets a switch point in front of the taught distance by the vertical minimum object separation.		
Sets a switch point at the follo	owing location:	and the switch point	
Model	Switch Point	distance flash alternately on the display.	
100 mm threaded barrel models	75		
300 mm threaded barrel models	200		
110 mm flush mount models	85		
310 mm flush mount models	210		
		-	
	Sets a switch point in front of distance by the vertical minim separation. Sets a switch point at the follor Model 100 mm threaded barrel models 300 mm threaded barrel models 110 mm flush mount models	Sets a switch point in front of the taught distance by the vertical minimum object separation.         Sets a switch point at the following location:         Model       Switch Point         100 mm threaded barrel models       75         300 mm threaded barrel models       200         110 mm flush mount models       85	

## 3.6.5 Dual (Intensity + Distance)

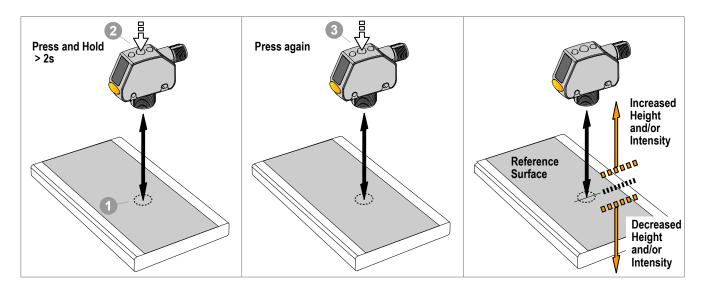
Dual (intensity + distance) TEACH records the distance and amount of light received from the reference surface. The output switches when an object passing between the sensor and the reference surface changes the perceived distance or amount of returned light. For more information on dual TEACH mode, see *Dual (Intensity + Distance) Mode* on page 30.



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NOTE: To use the following instructions, set the sensor to  $\frac{1}{2}$  =  $\frac{1}{2}$ . The DYN, FGS, and BGS indicators are amber.

NOTE: To program the sensor using remote input, remote input must be enabled (  $10^{10}$  = 52 ).



#### 1. Present the target.

Method	Action	Result
Push Button	Present the reference target.	The target's match percentage
Remote Input		displays

### 2. Start the TEACH mode.

Method	Action	Result
Push Button	Press and hold the TEACH button for more than 2 seconds.	Light Operate: SEE and On flash on the display. The DYN, FGS, and BGS indicators flash. Dark Operate: SEE and OFF flash on the display. The DYN, FGS, and BGS indicators flash.
Remote Input	No action required.	N/A

#### 3. Teach the sensor.

Method	Action	Result
Push Button	Press the TEACH button.	The switching threshold flashes
Remote Input	Single-pulse the remote input.	rapidly and the sensor returns to Run mode.

#### Table 6: Expected TEACH Behavior for Dual (Intensity + Distance) Mode

Condition	TEACH Result	Display
One valid reference surface is taught within sensing range	Sets a dual (intensity + distance) window centered around the taught reference surface. The $\pm$ window size is the previously used switching threshold, or 75% by default.	The switching threshold flashes on the display.
One reference surface is taught outside the sensing range	Sets a dual (intensity + distance) window centered around the taught reference surface that is outside the sensing range. The sensing conditions may not be as reliable.	ວມເັ flashes on the display.

Condition	TEACH Result	Display
One invalid TEACH Point	No reference surface is taught, the output will change when any object is detected.	Full flashes on the display.

## 3.7 Sync Master/Slave

Two Q4X sensors may be used together in a single sensing application. To eliminate crosstalk between the two sensors, configure one sensor to be the master and one to be the slave. In this mode, the sensors alternate taking measurements and the response speed doubles.



I mportant: The master sensor and the slave sensor must be programmed for the same Response Speed and Gain and Sensitivity settings. The master sensor and slave sensor must share a common power source.

- 1. Configure the first sensor as the master; navigate:  $\frac{1000}{1000} > \frac{1000}{1000}$ .
- 2. Configure the second sensor as the slave; navigate:  $10^{10}$  > 5202 .
- 3. Connect the gray (input) wires of the two sensors together.

## 4 Specifications

#### Sensing Beam

Visible red Class 1 laser, 655 nm

Supply Voltage (Vcc) 10 to 30 V dc

Power and Current Consumption, exclusive of load < 675 mW

Sensing Range—Threaded Barrel Models 300 mm models: 25 mm to 300 mm (0.98 in to 11.81 in) 100 mm models: 25 mm to 100 mm (0.98 in to 3.94 in)

Sensing Range—Flush Mount Models 310 mm models: 35 mm to 310 mm (1.38 in to 12.20 in) 110 mm models: 35 mm to 110 mm (1.38 in to 4.33 in)

Output Configuration

Threaded Barrel Models: Bipolar (1 PNP and 1 NPN) output Flush Mount Models: PNP or NPN output, depending on model

Output Rating 100 mA total maximum (protected against continuous overload and short circuit)

Off-state leakage current: < 5 µA at 30 V dc

PNP On-state saturation voltage: < 1.5 V dc at 100 mA load

NPN On-state saturation voltage: < 1.0 V dc at 100 mA load

Discrete Output Distance Repeatability

Table 7: Long-Range Models

Distance (mm)		Repeatability
Threaded Barrel Models	Flush Mount Models	
25 to 50 mm	35 to 60 mm	± 0.5 mm
50 to 300 mm	60 to 310 mm	± 1% of range

Table 8: Short-Range Models

Distance (mm)		Repeatability
Threaded Barrel Models	Flush Mount Models	
25 to 100 mm	35 to 110 mm	+/-0.2 mm

#### Remote Input

Allowable Input Voltage Range: 0 to Vcc

Active Low (internal weak pullup—sinking current): Low State < 2.0 V at 1 mA max.

Supply Protection Circuitry

Protected against reverse polarity and transient overvoltages

Response Speed

User selectable:

🥲 —1.5 m	nilliseconds
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-3 milliseconds

III —10 milliseconds

- 25 —25 milliseconds
- **50**—50 milliseconds

#### Beam Spot Size

Table 9: Beam Spot Size—Long-Range Models

Distance	Size (Horizontal × Vertical)	
Threaded Barrel Flush Mount Models Models		vertical)
25	35	2.6 mm × 1.0 mm
150	160	2.3 mm × 0.9 mm
300	310	2.0 mm × 0.8 mm

Table 10: Beam Spot Size—Short-Range Models

Distance	Size (Horizontal × Vertical)	
Threaded Barrel Flush Mount Models		vertical)
25	35	2.4 mm × 1.0 mm
50	60	2.2 mm × 0.9 mm
100	110	1.8 mm × 0.7 mm

#### Excess Gain—Threaded Barrel Models

Table 11: H ICH Excess Gain ( 55 d Excess Gain<sup>2</sup>)

Response Speed (ms)	Excess Gain—90% White Card			
Speed (IIIS)	at 25 mm	at 100 mm	at 300 mm	
1.5	200	100	20	
3	200	100	20	
10	1000 (500)	500 (250)	100 (50)	
25	2500 (1000)	1250 (500)	250 (100)	
50	5000 (2500)	2500 (1250)	500 (250)	

Excess Gain—Flush Mount Models

Table 12: H IGH Excess Gain ( Stod Excess Gain<sup>3</sup>)

Response Speed (ms)	Excess Gain—90% White Card			
Speed (IIIS)	at 35 mm	at 110 mm	at 310 mm	
1.5	200	100	20	
3	200	100	20	
10	1000 (500)	500 (250)	100 (50)	
25	2500 (1000)	1250 (500)	250 (100)	
50	5000 (2500)	2500 (1250)	500 (250)	

2 . 5td excess gain available in 10 ms, 25 ms, and 50 ms response speeds only

3

. Sted excess gain provides increased noise immunity

<sup>.</sup> SEd excess gain available in 10 ms, 25 ms, and 50 ms response speeds only

Delay at Power Up < 750 ms Maximum Torque Side mounting: 1 N·m (9 in·lbs) Nose mounting: 20 N·m (177 in·lbs) Ambient Light Immunity > 5,000 lux Connector Threaded Barrel Models: Integral 5-pin M12/Euro-style male quick disconnect (QD) Flush Mount Models: Integral 4-pin M12/Euro-style male quick disconnect (QD) Construction Housing: 316 L stainless steel Lens cover: PMMA acrylic Lightpipe and display window: polysulfone Environmental Rating

IEC IP67 per IEC60529 IEC IP68 per IEC60529

IEC IP69K per DIN40050-9

#### Vibration

MIL-STD-202G, Method 201A (10 Hz to 60 Hz, 0.06 inch (1.52 mm) double amplitude, 2 hours each along X, Y and Z axes), with sensor operating

#### Shock

MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y and Z axes, 18 total shocks), with sensor operating

Required Overcurrent Protection



WARNING: Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to http://www.bannerengineering.com.

Supply Wiring (AWG)	Required Overcurrent Protection (Amps)
20	5.0
22	3.0
24	2.0
26	1.0
28	0.8
30	0.5

Temperature Effect

 0.05 mm/°C at <125 mm (threaded barrel models)/< 135 mm (flush mount models)</li>
 0.35 mm/°C at 300 mm (threaded barrel models)/< 310 mm (flush mount models)</li>

 Chemical Compatibility

 Compatible with commonly used acidic or caustic cleaning and disinfecting chemicals used in equipment cleaning and sanitation. ECOLAB<sup>®</sup> certified.
 Compatible with typical cutting fluids and lubricating fluids used in machining centers

 Application Note

 For optimum performance, allow 10 minutes for the sensor to warm up

Operating Conditions

-10 °C to +50 °C (+14 °F to +122 °F) 35% to 95% relative humidity Storage Temperature

-25 °C to +75 °C (-13 °F to +167 °F)

Certifications



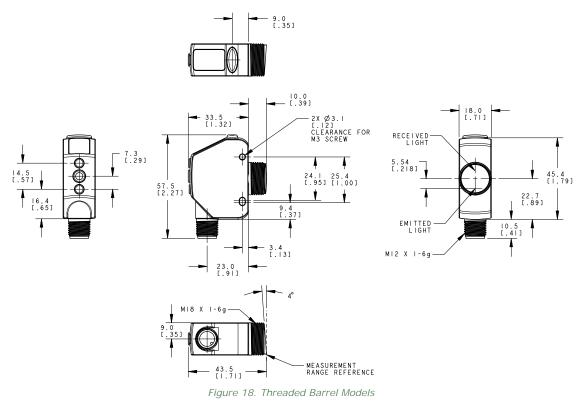
Class 2 power UL Environmental Rating: Type 1

ECOLAB<sup>®</sup> chemical compatibility certified

ECOLAB is a registered trademark of Ecolab USA Inc. All rights reserved.

### 4.1 Dimensions

All measurements are listed in millimeters [inches], unless noted otherwise.



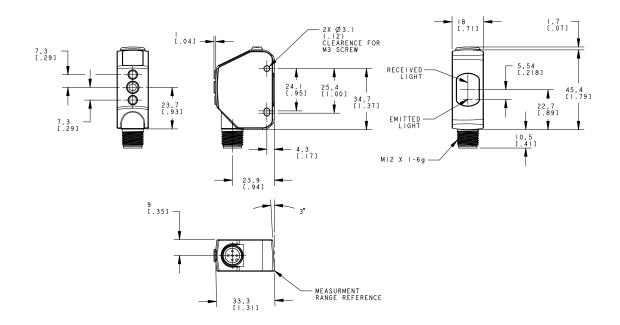
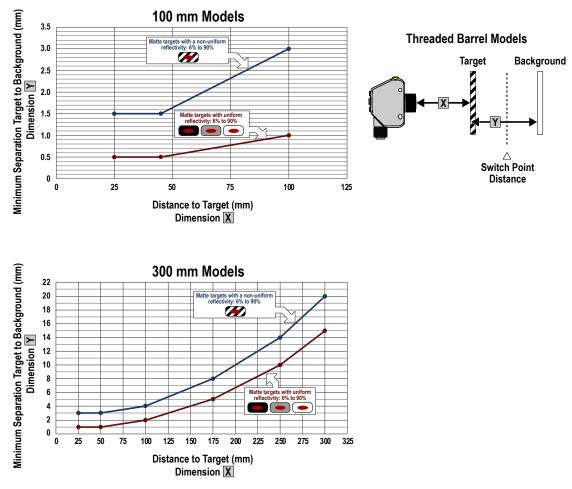


Figure 19. Flush Mount Models

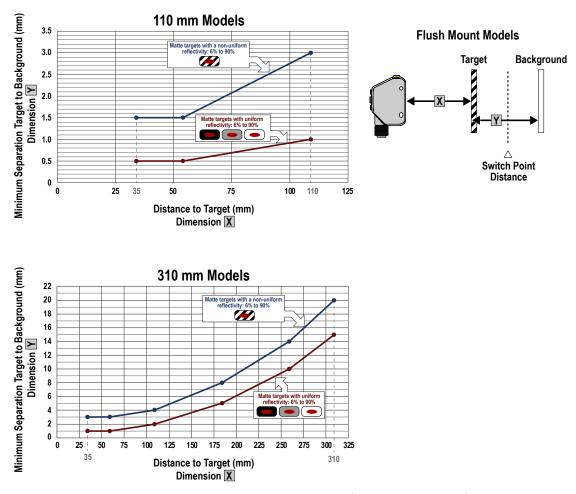
## 4.2 Performance Curves—Threaded Barrel Models



Minimum Separation Distance Between Target and Background for: Uniform and Non-Uniform Targets

Figure 20. Minimum Object Separation Distance (90% to 6% reflectance)

### 4.3 Performance Curves—Flush Mount Models



Minimum Separation Distance Between Target and Background for: Uniform and Non-Uniform Targets

Figure 21. Minimum Object Separation Distance (90% to 6% reflectance)

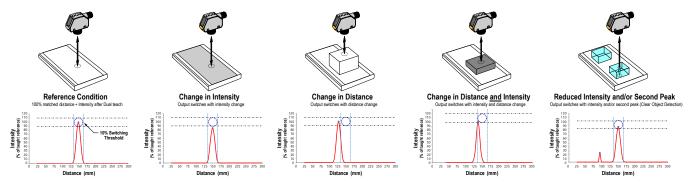
## 5 Additional Information

## 5.1 Dual (Intensity + Distance) Mode

In background suppression (DYN, 1-pt, 2-pt) and foreground suppression (FGS) TEACH modes, the Q4X sensor compares changes in the measured distance between the sensor and target to control the output state. Dual TEACH mode, dual intensity + distance window, expands the applications the Q4X can solve by combining distance-based detection with light intensity thresholds. In dual TEACH mode, the user teaches the Q4X a fixed reference surface, and the sensor compares intensity and distance readings against the reference surface it was taught. After teaching the reference target, the displayed value is calibrated to 100P, or a 100% match. When an object enters the sensor's field of view, the degree of consistency with the reference surface becomes lower and causes a change in sensor output.

In dual mode, you can detect when the target is present at the right distance and when it returns the right amount of light. This is useful in error-proofing applications where you need to know not only that the part is present (distance), but also that it is the correct part (intensity).

In dual mode, the Q4X requires a reference surface (far left). Once taught, the distance and intensity of the reference surface are recorded and used as a baseline. A user adjustable switching threshold is set, and changes in distance and/or intensity outside the switching threshold creates a sensor output change. The example above uses a 90% (90P) match condition with a 10% change in intensity and/or distance from the reference surface required to change the output state. The default-switching threshold is a 75% match to the reference condition (75P); this sets the threshold 25% from the distance and intensity of the reference surface. A transparent object can be detected either by a change in intensity, distance, or by a double peak reflection (far right).



The Q4X sensor can be taught non-ideal reference surfaces, such as surfaces outside of the sensor's 300 mm range, very dark surfaces, or even empty space. These situations may enable applications requiring a long range detection but are subject to typical diffuse mode detection challenges.

## 5.2 Dual Mode Reference Surface Considerations

Optimize reliable detection by applying these principals when selecting your reference surface, positioning your sensor relative to the reference surface, and presenting your target. The robust detection capabilities of the Q4X allows successful detection even under non-ideal conditions in many cases. Typical reference surfaces are metal machine frames, conveyor side rails, or mounted plastic targets. Contact Banner Engineering if you require assistance setting up a stable reference surface in your application.

- 1. Select a reference surface with these characteristics where possible:
  - Matte or diffuse surface finish
  - Fixed surface with no vibration
  - Dry surface with no build-up of oil, water, or dust
- 2. Position the reference surface between
  - 50 mm and 300 mm for 300 mm threaded barrel models
  - 50 mm and 100 mm for 100 mm threaded barrel models
  - 60 mm and 310 mm for 310 mm flush mount models
  - 60 mm and 110 mm for 110 mm flush mount models
- 3. Position the target to be detected as close to the sensor as possible, and as far away from the reference surface as possible.
- 4. Angle the sensing beam relative to the target and relative to the reference surface 10 degrees or more.

# 5.3 Dual Mode Considerations for Clear and Transparent Object Detection

The Q4X is able to detect the very small changes caused by transparent and clear objects. A transparent object can be detected either by a change in intensity, distance, or by a double-peak reflection.

The Q4X sensor can be taught non-ideal reference surfaces, such as surfaces outside of the sensor range or very dark surfaces. Teaching non-ideal reference surfaces may enable applications other than transparent or clear object detection, but best results for transparent or clear object detection require a stable reference surface.

The display shows the match percentage to the taught reference point. The user adjustable switch point defines the sensitivity and the output switches when the match percentage to the reference point crosses the switch point. Your specific application may require fine tuning of the switch point, but these values are the recommended starting values:

Switch point (%)	Typical Applications
75 (default)	Default, recommended for PET bottles and Trays
88	Recommended for thin films
50	Recommended for tinted brown, tinted green, or water-filled containers

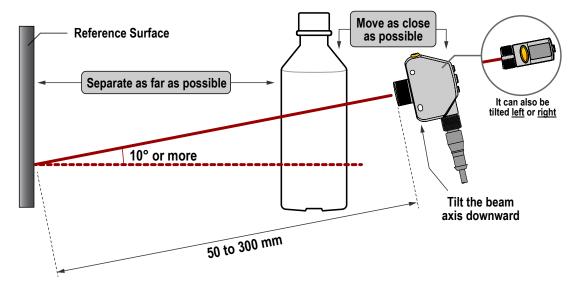
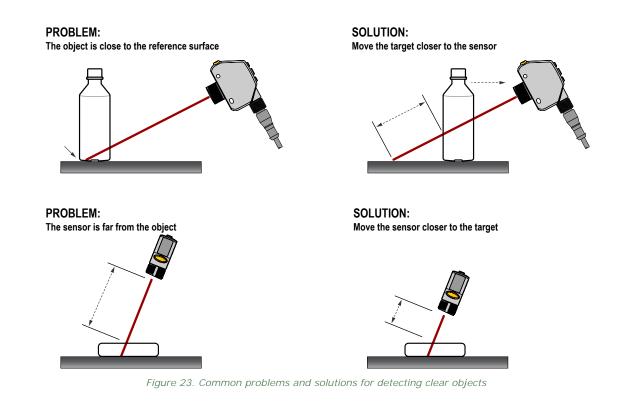


Figure 22. Mounting considerations



## 5.4 Abbreviations

The following table describes the abbreviations used on the sensor display and in this manual.

Abbreviation	Description
	No valid signal in range
999P	The sensor has not been taught
15ho	One-shot
158	First
Znd	Second
2-95	Two-point TEACH (static background suppression)
605	One-point background suppression
btn	Button
EnEL	Cancel
d ,5P	Display read
968	Output timing delay
81.89 8	Delay
dE (	Delay timer for one-shot
dăn	Dynamic background suppression
End	End—exit the sensor menu

Abbreviation	Description
£8-	Far zero reference location—the maximum range is 0 and the measurement increase as the target moves closer to the sensor
FGS	One-point window (foreground suppression)
Ful-L	Full range
58 m	Excess gain
H ICH	High excess gain mode
00 <sup>9</sup> 5	Input wire function
Loc	Lock/locked
Loff	Laser off
A855	Master
nERr	Near zero reference location—the end of the barrel is 0 and the measurement increase as the target moves further away from the sensor
obult	Object
oFFd	Off delay timer
ond	On delay timer
H588	Reset to factory defaults
588	Input wire = remote teach function
5668	Shift the Zero Reference Location after a TEACH
51.08	Slave
588	Response speed
558	Standard excess gain mode
5575	Start
Stop	Stop
bch	TEACH process selection
whee	Unlock/unlocked
	Saturated signal (too much light)
28-0	Zero-select the zero reference location

## 6 Troubleshooting

Table 13: Error Codes

Error Code	Description	Resolution
	No valid signal in range	Reposition the sensor or the target
บบบบ	The signal is saturated (too much light)	Reposition the sensor or the target to increase the detection distance, or increase the angle of incidence between the sensor and the target
EnnE	EEPROM fault	Contact Banner Engineering to resolve
Ennl	Laser fault	Contact Banner Engineering to resolve
Enno	Output short-circuited	Check the wiring for an electrical short circuit and to ensure that the wiring is correct
8665	System fault	Contact Banner Engineering to resolve

## 7 Accessories

## 7.1 Cordsets—Threaded Barrel Models

5-Pin Threaded M12/Euro-Style Cordsets—Single Ended					
Model	Length	Style	Dimensions	Pinout (Female)	
MQDC1-501.5	0.50 m (1.5 ft)		<u> </u> →		
MQDC1-506	1.83 m (6 ft)	Straight M12 x1			
MQDC1-515	4.57 m (15 ft)				
MQDC1-530	9.14 m (30 ft)			1 - 2	
MQDC1-506RA	1.83 m (6 ft)	Right-Angle         3 = Blue           11.18 <sup>m</sup> 4 = Blac			
MQDC1-515RA	4.57 m (15 ft)		-		1 Decum
MQDC1-530RA	9.14 m (30 ft)		1.26"] 30 Typ. [1.16"] M12 x 1 ↓ +	2 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray	

All measurements are listed in millimeters, unless noted otherwise.

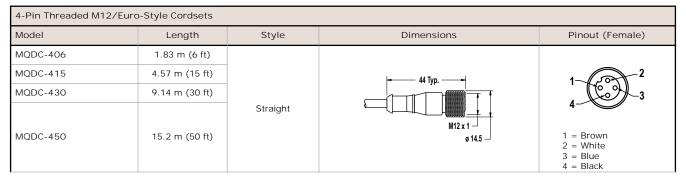
#### 5-Pin Threaded M12/Euro-Style Cordsets—Washdown Stainless Steel

Cable: PVC jacket and over-mold, EPDM o-ring, 316L coupling nut Environmental Rating: IEC IP69K

5-Pin Threaded M12/Euro-Style Cordsets—Washdown Stainless Steel				
Model	Length	Style	Style Dimensions Pinout (Female)	
MQDC-WDSS-0506	1.83 m (6 ft)			2
MQDC-WDSS-0515	4.57 m (15 ft)			$1 - \left( \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right)$
MQDC-WDSS-0530	9.14 m (30 ft)	Straight	Ø15.5 mm Ø4.8 mm	$4 - \frac{3}{5}$ $1 = \text{Brown}$ $2 = \text{White}$ $3 = \text{Blue}$ $4 = \text{Black}$ $5 = \text{Gray}$

## 7.2 Cordsets—Flush Mount Models

All measurements are listed in millimeters, unless noted otherwise.



4-Pin Threaded M12/Euro-Style Cordsets					
Model	Length	Style	Dimensions	Pinout (Female)	
MQDC-406RA	1.83 m (6 ft)	Right-Angle	, 32 Тур.		
MQDC-415RA	4.57 m (15 ft)		[1.26"]		
MQDC-430RA	9.14 m (30 ft)				
MQDC-450RA	15.2 m (50 ft)		M12 x 1 +++  σ 14.5 [0.57"] ++		

#### 4-Pin Threaded M12/Euro-Style Cordsets—Washdown Stainless Steel

Cable: PVC cable, stainless steel coupling nut, EPDM o-ring Environmental Rating: IEC IP69K

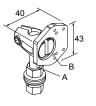
4-Pin Threaded M12/Euro-Style Cordsets—Washdown, Stainless Steel					
Model	Length	Style	Dimensions	Pinout (Female)	
MQDC-WDSS-0406	1.83 m (6 ft)	-			
MQDC-WDSS-0415	4.57 m (15 ft)			1-2-2	
MQDC-WDSS-0430	9.14 m (30 ft)	Straight	Ø15.5 mm	1 = Brown 2 = White 3 = Blue 4 = Black	

## 7.3 Brackets

All measurements are listed in millimeters, unless noted otherwise.

#### SMBQ4X..

- Swivel bracket with tilt and pan movement for precision adjustment
- . Easy sensor mounting to extruded rail T-slots
- Metric and inch size bolts available
- Side mounting of some sensors with the 3 mm screws included with the • sensor



#### $B~=~7~\times~M3~\times~0.5$

Model	Bolt Thread (A)
SMBQ4XFA	3/8 - 16 × 2¼ in
SMBQ4XFAM10	M10 - 1.5 × 50
SMBQ4XFAM12	n/a; no bolt included. Mounts directly to 12 mm ( $\frac{1}{2}$ in) rods

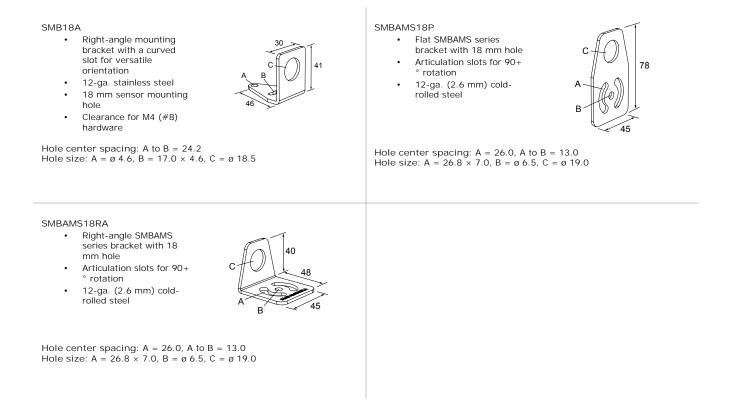
#### SMB18FA..

- Swivel bracket with tilt and pan movement for precision adjustment
- Easy sensor mounting to
- Metric and inch size bolts
- available 18 mm sensor mounting

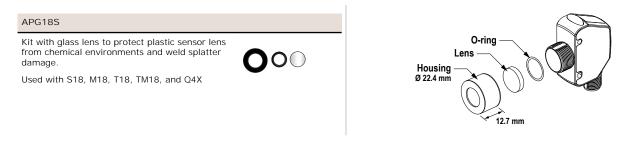
#### Hole size: B=ø 18.1

Model	Bolt Thread (A)
SMB18FA	3/8 - 16 × 2 in
SMB18FAM10	M10 - 1.5 × 50
SMB18FAM12	n/a; no bolt included. Mounts directly to 12 mm ( $\mathcal{V}_2$ in) rods

- extruded rail T-slots
- hole



### 7.4 Aperture Kits—Threaded Barrel Models

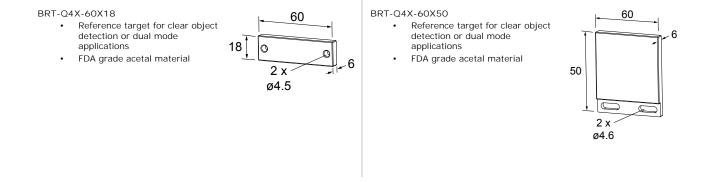


Additional Information

- · Borosilicate glass window protects the PMMA window from weld splatter and chemicals
- Adds 4.8 mm to the length of the threaded barrel
- Reduces excess gain by 30%; increase the response time to restore excess gain

### 7.5 Reference Targets

All measurements are listed in millimeters, unless noted otherwise.



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